Installation Notes

Prepare the environment

You'll need:

- A C++ compiler, preferably g++
- A working SystemC implementation
  - ?OSCI implementation
  - SystemCass
- Binutils and BFD for your target CPU, see Cross Compiler
- A ?Subversion client
- A recent ?Python interpreter
- A bourne-shell compatible, like bash
- ?SDL (for graphic utilities)
- xterm, the X11 terminal emulator

Getting SoCLib

Please note SVN repository contains ?`svn:externals` references to transparently checkout other repositories within SoCLib's one. This standard feature is well supported by ?vanilla Subversion client but is unsupported by most alternative clients. Please ensure your client does support `externals`.

```
$ cd where/to/put/soclib
$ svn co https://www.soclib.fr/svn/trunk/soclib soclib
```

Put `soclib/bin` in your `$PATH`, preferably add this line in your shell's startup scripts.

```
$ export PATH=$PATH:where/to/put/soclib/utils/bin
```

Compiling tools

Some tools need compilation before use:

```
$ cd where/to/put/soclib/utils/src
$ make
$ make install
```

Configuration

SystemC

You may edit [SoclibConf SoCLib's configuration file]. Out of the box, the only thing the configuration needs is setting an environment variable pointing to your SystemC implementation. Again this may preferably reside in your shell's startup scripts:

```
$ export SYSTEMC=/path/to/systemc
```

If you want to check, you should have a listing close to this one:

```
$ ls $SYSTEMC
AUTHORS  ChangeLog  LICENSE  README      docs     include
```

```
COPYING  INSTALL   NEWS    RELEASENOTES  examples  lib-linux
```

Cross-compilation tools

By default, platform examples expect cross-toolchains compiled as described in <u>Cross Compiler</u>. I.e. it expects `mipsel-unknown-elf-gcc`, `powerpc-unknown-elf-gcc` and `mb-gcc` (Xilinx ships a Microblaze compiler named it this way).

If you already have cross-toolchains compiled on your host, you can declare them in `~/.soclib/soft_compilers.conf`. For each architecture in `mipsel`, `powerpc` and `microblaze`, you may define:

```
<arch>_CC_PREFIX = ...
<arch>_CFLAGS = ...
<arch>_LDFLAGS = ...
```

For instance, if you want to use a mips cross-compiler configured for Linux (GNU+Glibc), you can declare:

```
mipsel_CC_PREFIX = mipsel-linux-elf-
mipsel_CFLAGS += -nostdinc
mipsel_LDFLAGS += -nostdlib
```

`nostdinc` and `nostdlib` disable default libraries (Glibc) from compilation and linking.

Pay attentions to default values in `/path/to/soclib/utils/conf/soft_flags.mk`, they may be of some usefulness. Dont directly modify `soft_flags.mk` unless you intend to commit your modifications. This is a versionned file !

Other paths

You should have cross-compilers in you path as well. For instance you should have a generic mipsel compiler toolsuite available as `mipsel-unknown-elf-*`.

If they are not in the `$PATH`, add them in:

```
$ export PATH=$PATH:/path/to/compiler/suite/bin
```

Testing

Let's compile a simple platform:

```
$ cd /path/to/soclib/soclib/platform/topcells/caba-vgmn-multi_timer-mipsel
$ make
[...]
$ ./simulation.x 1000000
```

If ever this fails, see if [SoclibConf SoCLib's configuration file] may help you.

FAQ

<u>Frequently asked questions</u>: When things goes wrong